MTi-610

- Small, IP51-rated IMU
- Factory-calibrated inertial data
- Full Graphical User Interface (GUI) and Software Development Kit (SDK) available

The MTi-610 is a Inertial Measurement Unit with a small form-factor design for deep integration into your application. Building on the proven Xsens MTi 600-series technology it enables a robust and easy to use motion tracking. It is designed for easy integration and seamless interfacing with other equipment.

The MTi-610 is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms including ROS.



- White label and OEM integration options available
- 3D models available on request

| IMU | performance |
|--------|-------------|
| Accele | rometer |

| Accelerometer | | Calibrated |
|------------------|-------------|------------|
| Gyroscope — | | Calibrated |
| Strapdown Integr | ation (SDI) | Yes |

Gyroscope

| Standard full range | 2000 deg/s |
|-------------------------|----------------|
| In-run bias stability | 8 deg/h |
| Bandwidth (-3dB) — | 520 Hz |
| Noise Density —— | 0.007 °/s/√Hz |
| g-sensitivity (calibr.) | 0.1 º/s/g |

Accelerometer Standard full range

| Starraar a ran range | -09 |
|-----------------------|-------------------|
| In-run bias stability | 10 (x,y) 15(z) μg |
| Bandwidth (-3dB) | 500 Hz |
| Noise Density | 60 μg/√Hz |

10 a

Magnetometer

| Standard full range ————— | +/- 8 G |
|---------------------------|---------|
| Total RMS noise ————— | 1 mG |
| Non-linearity | 0.2% |
| Resolution | 0.25 mG |

Barometer

| Standard full range ————— | 300-1250 hPa |
|---------------------------|------------------|
| Total RMS noise | 1.2 Pa |
| Relative accuracy | +/- 8 Pa (~0.5m) |

This document is informational and not binding.

Complete and detailed specifications are available at
mtidocs.movella.com

Mechanical

| IP-rating ———— | IP51 |
|---------------------------|---------------------------------------|
| Operating Temperature ——— | -40 to 85 °C |
| Casing material | PC-ABS |
| Mounting orientation ———— | No restriction, full 360° in all axes |
| Dimensions — | 28x31.5x13 mm |
| Connector — | Main: Phoenix Contact 16 pin, 1.27 mm |
| | pitch |
| Weight — | 8.9 g |
| Certifications | CE, FCC, RoHS |
| | |

Electrical

| Input voltage | 4.5 | to 24V |
|-------------------------|-----|--------|
| Power consumption (typ) | <0. | 5 W |

Interfaces / IO

| Interfaces ————— | UART, CAN, RS232 |
|-----------------------|----------------------------|
| Sync Options | SyncIn, SyncOut, ClockSync |
| Protocols — | Xbus, ASCII (NMEA) or CAN |
| Clock drift | 10 ppm (or external) |
| Output Frequency ———— | Up to 2kHz, 400Hz SDI |
| Built-in-self test | Gyr, Acc, Mag, Baro |

Software Suite

| Software Suite | |
|---------------------|----------------------------------|
| GUI (Windows/Linux) | MT Manager, Firmware updater, |
| | Magnetic Field Mapper |
| SDK (Example code) | C++, C#, Python, Matlab, Nucleo, |
| | public source code |
| Drivers ————— | LabVIEW, ROS, GO |
| Support —————— | Online manuals, community and |
| | knowledge base |



